

# UCH O'LCHAMLI NILPOTENT ALGEBRANING DIFFERENSIALLASHI LOKAL VA IKKI LOKAL DIFFERENSIALLASHI

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**Izoh:** *Differenziyallash matematikaning fundamental tushunchalaridan biri hisoblanadi. Differenziyallashlar algebra fanida ham muhim o'rin tutadi. Differenziyallashlarning turli umumlashmalari mavjud. Bular sarasiga antidifferenziyallashlar,  $\delta$ -differenziyallashlar, ternar differenziyallashlar va  $(\alpha, \beta, \gamma)$ -differenziyallashlar kiradi. Ushbu ishda uch o'lchamli nilpotent algebralarning differenziyallashi lokal va ikki lokal differenziyallashi isboti bilan ko'rsatilgan.*

**Kalit so'zlar:** Differenziyallash, Algebra, lokal differenziyallash va ikki lokal differenziyallash, chiziqli akslatirish.

## DIFFERENTIATION OF THREE-DIMENSIONAL NILPOTENT ALGEBRA, LOCAL AND TWO LOCAL DIFFERENTIATION

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**Abstract.** Differentiation is one of the fundamental concepts of mathematics. Differentiations also play an important role in algebra. There are various generalizations of differentiations. These include antidifferentiations,  $\delta$ -differentiations, ternary differentiations, and  $(\alpha, \beta, \gamma)$ -differentiations. In this paper, the differentiation of three-dimensional nilpotent algebras is shown by proving local and bilocal differentiation.

**Key words:** Differentiation, Algebra, local differentiation and two-local

differentiation, linear mapping.

## I. KIRISH

### 1-§. Masalaning qo'yilishi

Hozirgi kunda jahonda differensiyalashlar nazariyasi bilan bir qatorda, operator algebralarida lokal va 2-lokal differensiyalashlar nazariyasi ham muhim hisoblanadi. So'ngi 20 yil davomida fon Neyman algebralari  $C^*$ -algebralari va  $JB^*$ -uchliklarda lokal va 2-lokal differensiallashlar nazariyasini o'rganish bo'yicha samarali natijalarga erishildi. Lokal differensiallashlarni o'rganish 1990-yilda R.B.Kadison va D.R.Larson hamda A.S.Sururlar tomonidan boshlangan.

Ixtiyoriy uch o'lchamli nilpotent algebra bazislari  $\{e_1, e_2, e_3\}$  bo'lgan quyidagi o'zaro izomorf bo'lmagan algebralarning biriga izomorf bo'ladi:

$$N_1: e_1^2=e_2, e_2^2=e_3$$

$$N_2: e_1^2=e_2, e_2e_1=e_3, e_2^2=e_3$$

$$N_3: e_1^2=e_2, e_2e_1=e_3$$

$$N_4(\alpha): e_1^2=e_2, e_1e_2=e_3, e_2e_1=\alpha e_3$$

$$N_5: e_1^2=e_2$$

$$N_6: e_1^2=e_3, e_2^2=e_3$$

$$N_7: e_1e_2=e_3, e_2e_1=-e_3$$

$$N_8(\alpha): e_1^2=\alpha e_3, e_2e_1=e_3, e_2^2=e_3$$

## II. ADABIYOTLAR TAHLILI

Differensiallashning ko'plab umumlashmalari mavjud. Eng asosiy umumlashmasi bu lokal va 2-lokal umumlashmalari hisoblanadi. So'ngi yillarda ko'plab olimlar lokal va 2-lokal differensiallashlarga oid ko'plab maqolalar chop etishdi[1- 3]

Quyida biz to'rt o'lchamli nilpotent algebralarning lokal va ikki lokal differensiallashini keltiramiz.

**1-Ta'rif.** Agar  $d: L \rightarrow L$  chiziqli akslantirish  $F$  maydonda berilgan  $L$  algebradan olingan ixtiyoriy  $x, y$  elementlar uchun quyidagi shartni qanoatlantirsa

$$d(xy) = d(x)y + xd(y)$$

$U$  holda, akslantirish  $L$  algebrada differensiallash deb ataladi.

$d(x) = Ax$  chiziqli akslantirishni qaraylik, buyerda  $A - n \times n$  o'lchamli kvadrat matritsa. Ravshanki, agar  $L$  algebradan olingan ixtiyoriy  $x, y$  elementlar uchun

$$A(xy) = (Ax)y + x(Ay) \quad (1)$$

tenglik bajarilsa  $d(x) = Ax$  akslantirish qaralayotgan  $L$  algebra da differensiallashdan iborat bo'radi.

Endi esa lokal differensiallash tushunchasini keltiramiz.

**2-Ta'rif.**  $L$  algebra bo'lib undagi xar bir  $x \in L$  element uchun  $\Delta(x) = D_x(x)$  shartni qanoatlantiruvchi  $D_x: L \rightarrow L$  differensiallash mavjud bo'lsa, u holda  $\Delta: L \rightarrow L$  chiziqli akslantirish lokal differensiallash deb ataladi.

**1.1-Ta'rif.**  $L$  algebra bo'lib undagi har bir  $x \in L$  element uchun  $\Delta(x) = D_x(x)$  shartni qanoatlantiruvchi  $D_x: L \rightarrow L$  differensiallash mavjud bo'lsa, u holda  $\Delta: L \rightarrow L$  chiziqli akslantirish lokal differensiallash deb ataladi.

$N_1$  algebraning differensiallashini biz yuqorida 2.2-§ ishda ko'rib o'tganmiz

$$A = \begin{pmatrix} a_{1,1} & 0 & 0 \\ 0 & 2a_{1,1} & 0 \\ a_{3,1} & 0 & 4a_{1,1} \end{pmatrix}$$

bu yerda quyidagi belgilashni kiritamiz

$a_{1,1} = \alpha, a_{3,1} = \beta$  u holda  $A$  matritsa bunday ko'rinishga o'tadi.

$$A = \begin{pmatrix} \alpha & 0 & 0 \\ 0 & 2\alpha & 0 \\ \beta & 0 & 4\alpha \end{pmatrix}$$

Quyidagi teoremda  $N_1$  algebra uchun  $\Delta: N_1 \rightarrow N_1$  akslantirishni qaraylik.

**3.1.1-Teorema.**  $N_1$  algebraning har qanday chiziqli lokal differensiallashi differensiallashdan iborat.

Isbot.  $\Delta$  ixtiyoriy lokal differensiallashi bo'lsin. Barcha  $x \in N_1$  uchun ta'rif bo'yicha  $\Delta(x) = D_x(x)$  differensiallashi mavjud.

1- teorema ga ko'ra,  $D_x$  differensiallashi quyidagi matritsa ko'rinishiga ega:

$$A_x = \begin{pmatrix} \alpha_x & 0 & 0 \\ 0 & 2\alpha_x & 0 \\ \beta_x & 0 & 4\alpha_x \end{pmatrix}.$$

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Xususan  $\Delta(e_1) = D_{e_1}e_1, \Delta(e_2) = D_{e_2}e_2, \Delta(e_3) = D_{e_3}e_3$

tengliklarni qanoatlantiruvchi  $D_{e_1}, D_{e_2}, D_{e_3}$  matritsalar mavjud.  $A$  matritsani

quyidagicha quraylik:

$$A = \begin{pmatrix} \alpha_{e_1} & 0 & 0 \\ 0 & 2\alpha_{e_2} & 0 \\ \beta_{e_1} & 0 & 4\alpha_{e_3} \end{pmatrix}.$$

$\Delta$  chiziqli bo'lgani uchun

$$\Delta(x+y) = \Delta(x) + \Delta(y), \forall x, y \in N_1(1)$$

tenglik o'rinli.

Bu tenglikka ko'ra

$$\Delta(e_1+e_2) = \alpha_{e_1+e_2} e_1 + \beta_{e_1+e_2} e_3 + 2\alpha_{e_1+e_2} e_2$$

$$\Delta \dot{!}$$

tengliklarga ega bo'lamiz. Bunda bazis elementlarining koeffitsientlarini taqqoslab, biz quyidagilarga erishamiz:

$$\alpha_{e_1+e_2} = \alpha_{e_1}, \beta_{e_1+e_2} = \beta_{e_1}, \alpha_{e_1+e_2} = \alpha_{e_2}.$$

Bundan esa  $\alpha_{e_1} = \alpha_{e_2}$ .

(1) tenglikdan foydalanib,

$$\Delta(e_2+e_3) = 2\alpha_{e_2+e_3} e_2 + 4\alpha_{e_2+e_3} e_3,$$

$$\Delta \dot{!}.$$

Yana bazis elementlarining koeffitsientlarini taqqoslab, biz quyidagilarga erishamiz:

$$\alpha_{e_2+e_3} = \alpha_{e_2}, \alpha_{e_2+e_3} = \alpha_{e_3}.$$

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Bundan esa  $\alpha_{e_2} = \alpha_{e_3}$  bo'ladi.

Shunday qilib, biz  $\Delta$  lokal differensiallash quyidagi shaklga ega ekanligini bilib olamiz:

$$\Delta = \begin{pmatrix} \alpha_{e_1} & 0 & 0 \\ 0 & 2\alpha_{e_1} & 0 \\ \beta_{e_1} & 0 & 4\alpha_{e_1} \end{pmatrix}$$

Teorema isbotlandi.

$$\alpha_{e_1+e_2} = \alpha_{e_1},$$

Bundan esa  $\alpha_{e_1+e_2} = \alpha_{e_1}$ .

Shunday qilib, biz  $\Delta$  lokal differensiallash quyidagi shaklga ega

ekanligini bilib olamiz:

$$\Delta = \begin{pmatrix} 0 & 0 & 0 \\ 0 & 0 & 0 \\ \alpha_{e_1} & 0 & 0 \end{pmatrix}$$

Teorema isbotlandi.

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